

Existence and Uniqueness of Solutions for a New Model of a Triple Nonlinear Elliptic System with Various Boundary Conditions

Ahmed Abdulrahman Muhsen and Jamil Amir Ali Al-Hawasy

*Department of Mathematics, Mustansiriyah University, Palestine Str., 10052 Baghdad, Iraq
{ahmedam2024, jhawassy17}@uomustansiriyah.edu.iq*

Keywords: Dirichlet Conditions, Mixed Boundary Conditions, Minty-Browder Theorem, Numann Conditions, Robin Condition, Triple Nonlinear Elliptic Partial Differential Equations.

Abstract: As is known, the investigation for finding the numerical solution for any mathematical model need at first to check the existence of unique analytic solution for this model. For this reason, the study for existence of a unique solution (the solvability) for any mathematical model is considered important. This importance encouraged us to devote about the study for the solvability of a new mathematical model describes by a system of triple nonlinear elliptic PDEs (TNLEPDEs) with various kinds of boundary conditions (BCs), as the Dirichlet (DBC), the Neumann(NBCs), the Robin(RBCs) and the Mixed BCs(MBCs). In this study, the weak form (WF) for the TNLEPDEs associated with each type of the above mentioned BCs is formulated in infinite dimensional space. Then the existence theorem of a unique solution for each type of the resulted weak form is proved by utilizing the Minty-Browder theorem (MBTH), with the help of the Friedrichs- Poincare inequality (FPI) when the BCs are of homogeneous kind (HBCs) and with the help of the generalization Friedrichs- Poincare inequality (GFPI) besides to the trace operator (TRO) when the kinds of the BCs are nonhomogeneous (NHBCs).

1 INTRODUCTION

As it knowns, many different types of real life problems in various branch of the sciences are expressed by mathematical models, like electromagnetic waves [1], the flow of fluids [2], physics of fluid [3], the blood of flow [4], molecules structure [5], vibrations of solids [6], mechanics of quantum [7], interactions of electrons and photons [8], the transfer of heat [9], and optimal control [10], they can be described as mathematical models which are usually represented by ODEs or PDEs.

Similarly, the mathematical models, the differential equations had also the major role in modern studies mathematics and their applications [11]-[13]. Therefore, many investigators had interested about the study of the existence and uniqueness for various types of “single” PDEs, especially those which were studied in [14]-[16].

The investigating of the existence and uniqueness of the solution of the PDEs are considered the cornerstone to investigate the ability to find the solutions of the PDEs analytically, and in addition it helps and encourages to investigate the numerical

solution of these problems who's their analytic solutions are difficult to determine. We can say that, without any knowledge about the solvability of any PDEs, no one can try to find the solutions neither analytically nor numerically. From the above studies and as a result, this paper is devoted about studying the solvability (in infinite dimension) of the proposed TNLEPDEs with different types of the boundary conditions (BCs), including that the Dirichlet (DBC), the Neumann (NBCs), the Robin (RBCs) and the mixed BCs (MBCs). At first the WF of the proposed TNLEPDEs with each kind of the four BCs is found. Then, the existence theorem of a unique triple solution (TRS) of each resulted WF is demonstrated under appropriate hypotheses by utilizing the MBTH and with the help of the (PFI) when the BCs is homogenous (HBCs), and by the help of the generalization PFI (GPFI) besides to the trace operator (TRO) when the BCs is nonhomogeneous (NHBCs). As we mentioned above, the outcomes of this manuscript are considered much important and will help many investigators who are interested about solvability of mathematical control problems [17]-[19], and of many other real life problems analogs of the considered models here.

2 MANUSCRIPT PREPARATION

This section includes some basic definition, theorems and lemmas which are interested in our work, and then a description for the problem formulation.

2.1 Basic Concepts

Definition 2.1.1 [20]. A function $k(x, y): \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}^M$ is said to be of a “Carathéodory type” if it is continuous with respect to y for fixed $x \in \Omega$ and it is measurable w.r.t. $x \in \Omega$ for fixed $y \in \mathbb{R}^N$.

Theorem 2.1.2 [21]. Let x and y be two elements in an inner product space with norm, then $|(x, y)| \leq \|x\| \|y\|$.

Theorem 2.1.3 (MBTH) [22]. Let V be a reflexive Banach space and V^* be its dual space. Consider the continuous nonlinear map: $V \rightarrow V^*$, s.t.

$\langle Ay_1 - Ay_2, y_1 - y_2 \rangle > 0$, for $y_1 \neq y_2, \forall y_1, y_2 \in V$, and $\lim_{\|y\|_{H_0^1(\Omega)} \rightarrow \infty} \frac{\langle Ay, y \rangle}{\|y\|_{H_0^1(\Omega)}} \rightarrow \infty$.

Then there exists a unique solution $y \in V$ of the equation $Ay = f$, for any $f \in V^*$.

Lemma 2.1.4 (PFI)[23]. Let Ω be any bounded Lipschitz domain [24], then there exists a positive constant $c(\Omega) > 0$, (depends on Ω only), for which the following inequality holds

$$\int_{\Omega} |y|^2 dx \leq c(\Omega) \int_{\Omega} |\nabla y|^2 dx, (\forall y \in H_0^1(\Omega)).$$

Lemma 2.1.5 (GPFI) [25]. Let $\Omega \subset \mathbb{R}^N$ be Lipschitz bounded domain and let $\Gamma_1 \subset \Gamma$ be a measurable set such that $|\Gamma_1| > 0$. Then there exists a constant $c(\Gamma_1) > 0$, independent of y , s.t.

$$\|y\|_{H^1(\Omega)}^2 \leq c(\Gamma_1) (\int_{\Omega} |\nabla y|^2 dx + (\int_{\Gamma_1} y ds)^2), \text{ for all } y \in H^1(\Omega).$$

Proposition 2.1.6 [26]. Let $f: \Omega \times \mathbb{R}^n \rightarrow \mathbb{R}^m$ be of the Carathéodory type defined in the measurable subset $\Omega \subset \mathbb{R}^n$, s.t.

$$\|f(x, y)\| \leq \varphi(x) + \xi(x) \|y\|^\alpha, \forall x \in \Omega, y \in L^P(\Omega),$$

where $\varphi \in L^1(\Omega)$, $\xi \in L^{\frac{P}{P-\alpha}}(\Omega)$, and $1 \leq \alpha \leq P$, if $1 \leq P < \infty$, and $\xi \equiv 0$, if $P = \infty$.

Then $F(y) = \int_{\Omega} f(x, y(x)) dx$ is continuous on $L^P(\Omega)$.

Theorem 2.1.7 (TRP) [27]. Let $\Omega \subset \mathbb{R}^d$ be a bounded Lipschitz domain with boundary $\Gamma = \partial\Omega$, then the following TRO exists $T_0: H^1(\Omega) \rightarrow L^2(\Gamma)$, s.t., $T_0 u = u|_{\Gamma}$, and $\|T_0 u\|_{L^2(\Gamma)} \leq c \|u\|_{H^1(\Omega)}$,

where $c = c(\Omega, d)$ be a suitable constant and $T_0 u$ represents the trace of u on Γ .

2.2 The Proposed Problem

Let $\Omega \subset \mathbb{R}^2$ be any open bounded Lipschitz domain with boundary $\Gamma = \partial\Omega$, then the TNLEPDEs with the HDBC are:

$$A_1 y_1 + B_1 y_1 + c_1(x) y_1 - d_1(x) y_2 + d_2(x) y_3 + f_1(x, y_1) = h_1(x), \text{ in } \Omega \quad (1)$$

$$A_2 y_2 + B_2 y_2 + c_2(x) y_2 + d_1(x) y_1 - d_3(x) y_3 + f_2(x, y_2) = h_2(x), \text{ in } \Omega \quad (2)$$

$$A_3 y_3 + B_3 y_3 + c_3(x) y_3 - d_2(x) y_1 + d_3(x) y_2 + f_3(x, y_3) = h_3(x), \text{ in } \Omega \quad (3)$$

$$y_1 = 0, \text{ on } \Gamma. \quad (4)$$

$$y_2 = 0, \text{ on } \Gamma \quad (5)$$

$$y_3 = 0, \text{ on } \Gamma \quad (6)$$

where $x = (x_1, x_2), \vec{y} = (y_1, y_2, y_3) \in (H_0^2(\Omega))^3$,

$$A_l y_l = - \sum_{i,j=1}^2 \frac{\partial}{\partial x_i} \left(a_{lij}(x) \frac{\partial y_l}{\partial x_j} \right), \quad l = 1, 2, 3,$$

$B_l y_l = \sum_{i=1}^2 b_{li}(x) \frac{\partial y_l}{\partial x_i}, \quad l = 1, 2, 3, \quad c_l, d_l \in L^\infty(\Omega),$
 $c_l, d_l \geq 0, \quad b_{li}, a_{lij} \in L^\infty(\Omega) \quad b_{li} \geq \beta_{li} > 0, \quad a_{lij} \geq \alpha_{lij} > 0, \forall l = 1, 2, 3, \quad \forall i, j = 1, 2$ and the functions $f_l(x, y_l), h_l(x) \in L^2(\Omega)$ for $l = 1, 2, 3$ are of the type of Carathéodory on $\Omega \times \mathbb{R}$ and on Ω resp.

2.3 The Weak Formulation of the System

The WF of ((1)-(6)) resulted by multiplying them by the “test function [28]” $v_l \in V = H_0^1(\Omega)$, ($l = 1, 2, 3$), then taking the integral and finally by utilizing the general Green’s theorem [29] for the terms that have 2nd order of partial derivatives, to get:

$$\int_{\Omega} \sum_{i,j=1}^2 a_{1ij} \frac{\partial y_1}{\partial x_i} \frac{\partial v_1}{\partial x_j} dx + \int_{\Omega} \sum_{i=1}^2 b_{1i}(x) \frac{\partial y_1}{\partial x_i} v_1 dx + \int_{\Omega} [c_1(x) y_1 v_1 - d_1(x) y_2 v_1 + d_2(x) y_3 v_1] dx + \int_{\Omega} f_1(x, y_1) v_1 dx = \int_{\Omega} h_1 v_1 dx \quad (7)$$

$$\int_{\Omega} \sum_{i,j=1}^2 a_{2ij} \frac{\partial y_2}{\partial x_i} \frac{\partial v_2}{\partial x_j} dx + \int_{\Omega} \sum_{i=1}^2 b_{2i}(x) \frac{\partial y_2}{\partial x_i} v_2 dx + \int_{\Omega} [c_2(x) y_2 v_2 - d_1(x) y_1 v_2 - d_3(x) y_3 v_2] dx + \int_{\Omega} f_2(x, y_2) v_2 dx = \int_{\Omega} h_2 v_2 dx \quad (8)$$

$$\begin{aligned} & \int_{\Omega} \sum_{i,j=1}^2 a_{3ij} \frac{\partial y_3}{\partial x_i} \frac{\partial v_3}{\partial x_j} dx + \\ & \int_{\Omega} \sum_{i=1}^2 b_{3i}(x) \frac{\partial y_3}{\partial x_i} v_3 dx + \int_{\Omega} [c_3(x) y_3 v_3 - \\ & d_2(x) y_1 v_3 + d_3(x) y_2 v_3] dx + \\ & \int_{\Omega} f_3(x, y_3) v_3 dx = \int_{\Omega} h_3 v_3 dx \end{aligned} \quad (9)$$

By gathering ((7)-(9)), they give

$$\langle \bar{A}(\vec{y}), \vec{v} \rangle = (\vec{F}(x), \vec{v}), \quad (10)$$

where $\bar{A}: \vec{V} \rightarrow \vec{V}^*$, with $\vec{V} = V \times V \times V$ and $\vec{V}^*$ is the dual of $\vec{V}$, s.t.

$$\langle \bar{A}(\vec{y}), \vec{v} \rangle = a(\vec{y}, \vec{v}) + (f_1(x, y_1), v_1)_{\Omega} + (f_2(x, y_2), v_2)_{\Omega} + (f_3(x, y_3), v_3)_{\Omega} \quad (11)$$

$$\begin{aligned} a(\vec{y}, \vec{v}) = & a_1(y_1, v_1) + b_1(y_1, v_1) + \\ & (c_1 y_1, v_1)_{\Omega} - (d_1 y_2, v_1)_{\Omega} + (d_2 y_3, v_1)_{\Omega} + \\ & a_2(y_2, v_2) + b_2(y_2, v_2) + (c_2 y_2, v_2)_{\Omega} + \\ & (d_1 y_1, v_2)_{\Omega} - (d_3 y_3, v_2)_{\Omega} + a_3(y_3, v_3) + \\ & b_3(y_3, v_3) + (c_3 y_3, v_3)_{\Omega} - (d_2 y_1, v_3)_{\Omega} + \\ & (d_3 y_2, v_3)_{\Omega} \end{aligned} \quad (12)$$

where $a_l(y_l, v_l) = \sum_{i,j=1}^2 a_{lij} \frac{\partial y_l}{\partial x_i} \frac{\partial v_l}{\partial x_j}$, for $l = 1, 2, 3$

$b_l(y_l, v_l) = \sum_{i=1}^2 b_{li}(x) \frac{\partial y_l}{\partial x_i} v_l$, for $l = 1, 2, 3$

$$(\vec{F}(x), \vec{v}) = (h_1(x), v_1)_{\Omega} + (h_2(x), v_2)_{\Omega} + (h_3(x), v_3)_{\Omega} \quad (13)$$

2.3.1 Assumptions

The functions $f_l(x, y_l)$ for $l = 1, 2, 3$ are of the type Carathéodory and monotone [30] w.r.t. y_l , $\forall x \in \Omega$, s.t.

- 1) $|f_l(x, y_l)| \leq \phi_l(x) + \bar{c}_l |y_l|$, $\forall (x, y_l) \in \Omega \times \mathbb{R}$ with $\phi_l \in L^2(\Omega)$, $\bar{c}_l \geq 0$.
- 2) $f_l(x, 0) = 0$, $\forall x \in \Omega$.

2.4 Solvability of the Triple Nonlinear Homogeneous Problem

The solvability of WF (10) is proved in the following theorem.

Theorem 2.4.1. The WF (10) owns a unique triple solution (TRS) $\vec{y} \in (H_0^1(\Omega))^3$, if assumptions 2.3.1 are held with f_1 is strictly monotone.

Proof. The proof resulted through utilizing Theorem 2.1.3, so let be started by proving that $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ in the LHS of (10) is coercive, as follows:

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle = & a_1(y_1, v_1) + b_1(y_1, v_1) + \\ & (c_1 y_1, v_1)_{\Omega} - (d_1 y_2, v_1)_{\Omega} + \\ & (d_2 y_3, v_1)_{\Omega} + a_2(y_2, v_2) + b_2(y_2, v_2) + \\ & (c_2 y_2, v_2)_{\Omega} + (d_1 y_1, v_2)_{\Omega} - (d_3 y_3, v_2)_{\Omega} + \\ & a_3(y_3, v_3) + b_3(y_3, v_3) + (c_3 y_3, v_3)_{\Omega} - \\ & (d_2 y_1, v_3)_{\Omega} + \\ & (d_3 y_2, v_3)_{\Omega} + (f_1(x, y_1), v_1)_{\Omega} + \\ & (f_2(x, y_2), v_2)_{\Omega} + (f_3(x, y_3), v_3)_{\Omega} \end{aligned} \quad (14)$$

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle = & \int_{\Omega} \sum_{i,j=1}^2 a_{1ij}(x) \frac{\partial y_1}{\partial x_i} \frac{\partial y_1}{\partial x_j} dx + \\ & \int_{\Omega} \sum_{i=1}^2 b_{1i}(x) \frac{\partial y_1}{\partial x_i} y_1 dx + \int_{\Omega} c_1(x) y_1 y_1 dx - \\ & \int_{\Omega} d_1(x) y_2 y_1 dx + \int_{\Omega} d_2(x) y_3 y_1 dx + \\ & \int_{\Omega} \sum_{i,j=1}^2 a_{2ij}(x) \frac{\partial y_2}{\partial x_i} \frac{\partial y_2}{\partial x_j} dx + \int_{\Omega} c_2(x) y_2 y_2 dx + \\ & \int_{\Omega} \sum_{i=1}^2 b_{2i}(x) \frac{\partial y_2}{\partial x_i} y_2 dx + \int_{\Omega} d_1(x) y_1 y_2 dx - \\ & \int_{\Omega} d_3(x) y_3 y_2 dx + \int_{\Omega} \sum_{i,j=1}^2 a_{3ij}(x) \frac{\partial y_3}{\partial x_i} \frac{\partial y_3}{\partial x_j} dx + \\ & \int_{\Omega} \sum_{i=1}^2 b_{3i}(x) \frac{\partial y_3}{\partial x_i} y_3 dx + \\ & \int_{\Omega} c_3(x) y_3 y_3 dx - \int_{\Omega} d_2(x) y_1 y_3 dx + \\ & \int_{\Omega} d_3(x) y_2 y_3 dx + \int_{\Omega} f_1(x, y_1) y_1 dx + \\ & \int_{\Omega} f_3(x, y_3) y_3 dx + \int_{\Omega} f_2(x, y_2) y_2 dx \end{aligned}$$

Since $a_{lij}(x) \geq \alpha_{lij} > 0$, ($\forall l = 1, 2, 3, \forall i, j = 1, 2$), and by utilizing assumptions 2.3.1, with putting

$\frac{\partial y_l}{\partial x_i} y_l = \frac{1}{2} \frac{\partial}{\partial x_i} (y_l^2)$, in the 2nd, the 8th and the 14th

terms, then:

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle \geq & \alpha_{1ij} \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx + \\ & \int_{\Omega} c_1(x) |y_1|^2 dx \\ & + \sum_{i=1}^2 \int_{\Omega} b_{1i}(x) \frac{1}{2} \frac{\partial}{\partial x_i} (y_1^2) dx + \\ & + \alpha_{2ij} \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx \\ & + \sum_{i=1}^2 \int_{\Omega} b_{2i}(x) \frac{1}{2} \frac{\partial}{\partial x_i} (y_2^2) dx + \\ & + \int_{\Omega} c_2(x) |y_2|^2 dx + \\ & + \sum_{i=1}^2 \int_{\Omega} b_{3i}(x) \frac{1}{2} \frac{\partial}{\partial x_i} (y_3^2) dx + \\ & + \int_{\Omega} c_3(x) |y_3|^2 dx + \\ & + \alpha_{3ij} \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx + \\ & + \int_{\Omega} (f_1(x, y_1) - f_1(x, 0)) (y_1 - 0) dx + \\ & + \int_{\Omega} (f_2(x, y_2) - f_2(x, 0)) (y_2 - 0) dx + \\ & + \int_{\Omega} (f_3(x, y_3) - f_3(x, 0)) (y_3 - 0) dx. \end{aligned} \quad (15)$$

Since f_l is monotone w.r.t. y_l , and letting $\alpha = \min(\alpha_{lij})$, $\forall l = 1, 2, 3, \forall i, j = 1, 2$, utilizing integrating by parts in the 2nd, the 5th and the 8th terms on the RHS of (15), to obtain:

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle &\geq \alpha \left(\sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx + \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx + \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx \right) \\ &+ \int_{\Omega} \left(c_1(x) - \frac{1}{2} \sum_{i=1}^2 \frac{\partial b_{1i}}{\partial x_i} \right) |y_1|^2 dx \\ &+ \int_{\Omega} \left(c_2(x) - \frac{1}{2} \sum_{i=1}^2 \frac{\partial b_{2i}}{\partial x_i} \right) |y_2|^2 dx \\ &+ \int_{\Omega} \left(c_3(x) - \frac{1}{2} \sum_{i=1}^2 \frac{\partial b_{3i}}{\partial x_i} \right) |y_3|^2 dx \end{aligned} \quad (16)$$

Select b_{li} and c_l , for $l = 1, 2, 3, \forall i = 1, 2$, s.t.

$$c_l(x) - \frac{1}{2} \sum_{i=1}^2 \frac{\partial b_{li}}{\partial x_i} \geq 0, \quad x \in \bar{\Omega},$$

which gives

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle \geq \alpha \sum_{l=1}^3 \|\Delta y_l\|_{L^2(\Omega)}^2. \quad (17)$$

Then by Lemma 2.1.4

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle \geq \frac{\alpha}{C_*} \sum_{l=1}^3 \|y_l\|_{L^2(\Omega)}^2. \quad (18)$$

Adding (17) with (18), setting $C_0 = \min(\alpha, \frac{\alpha}{C_*})$, to get:

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle &\geq C_0 \sum_{l=1}^3 (\|y_l\|_{L^2(\Omega)}^2 + \|\Delta y_l\|_{L^2(\Omega)}^2) = \\ &C_0 \sum_{l=1}^3 \|y_l\|_{H_0^1}^2. \end{aligned}$$

Thus:

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle \geq C_0 \|\vec{y}\|_{(H_0^1(\Omega))^3}^2. \quad (19)$$

On other hand, since $a_{lij}(x), b_{li}(x), c_l(x), d_l(x) \in L^\infty(\Omega)$, ($\forall l = 1, 2, 3, \forall i = 1, 2$), so:

$$\left| \int_{\Omega} \sum_{i,j=1}^2 a_{lij}(x) \frac{\partial y_l}{\partial x_i} \frac{\partial v_l}{\partial x_j} dx \right| \leq \sum_{i,j=1}^2 \mu_l \left| \int_{\Omega} \frac{\partial y_l}{\partial x_i} \frac{\partial v_l}{\partial x_j} dx \right| \quad (20)$$

$$\left| \int_{\Omega} \sum_{i=1}^2 b_{li}(x) \frac{\partial y_l}{\partial x_i} v_l dx \right| \leq \sum_{i=1}^2 \bar{\mu}_l \left| \int_{\Omega} \frac{\partial y_l}{\partial x_i} v_l dx \right| \quad (21)$$

$$\left| \int_{\Omega} c_l(x) y_l v_l dx \right| \leq \bar{\bar{\mu}}_l \left| \int_{\Omega} y_l v_l dx \right| \quad (22)$$

$$\left| \int_{\Omega} d_l(x) y_{3-l} v_l dx \right| \leq \bar{\bar{\bar{\mu}}}_1 \left| \int_{\Omega} y_{3-l} v_l dx \right| \quad (23)$$

$$\left| \int_{\Omega} d_l(x) y_{4-l} v_l dx \right| \leq \bar{\bar{\bar{\mu}}}_2 \left| \int_{\Omega} y_{4-l} v_l dx \right| \quad (24)$$

$$\left| \int_{\Omega} d_l(x) y_{5-l} v_l dx \right| \leq \bar{\bar{\bar{\mu}}}_3 \left| \int_{\Omega} y_{5-l} v_l dx \right| \quad (25)$$

where $\mu_l = \max_{x \in \Omega} |a_{lij}(x)|$, $\bar{\mu}_l = \max_{x \in \Omega} |b_{li}(x)|$, $\bar{\bar{\mu}}_l = \max_{x \in \Omega} |c_l(x)|, \forall l = 1, 2, 3$, $(\bar{\bar{\bar{\mu}}}_1 = \max_{x \in \Omega} |d_l(x)|,$

$\forall l = 1, 2$), $(\bar{\bar{\bar{\mu}}}_2 = \max_{x \in \Omega} |d_l(x)|, \forall l = 1, 3)$, and $(\bar{\bar{\bar{\mu}}}_3 = \max_{x \in \Omega} |d_l(x)|, \forall l = 2, 3)$.

Therefore, by (20)-(25):

$$\begin{aligned} |a(\vec{y}, \vec{v})| &\leq \sum_{l=1}^3 \sum_{i,j=1}^2 \mu_l \left| \int_{\Omega} \frac{\partial y_l}{\partial x_i} \frac{\partial v_l}{\partial x_j} dx \right| + \\ &\sum_{l=1}^3 \sum_{i,j=1}^2 \bar{\mu}_l \left| \int_{\Omega} \frac{\partial y_l}{\partial x_i} v_l dx \right| + \sum_{l=1}^3 \bar{\bar{\mu}}_l \left| \int_{\Omega} y_l v_l dx \right| + \\ &\bar{\bar{\bar{\mu}}}_1 \left| \int_{\Omega} y_{3-l} v_l dx \right| + \bar{\bar{\bar{\mu}}}_2 \left| \int_{\Omega} y_{4-l} v_l dx \right| + \\ &\bar{\bar{\bar{\mu}}}_3 \left| \int_{\Omega} y_{5-l} v_l dx \right|. \end{aligned}$$

By utilizing theorem 2.1.2, to get:

$$\begin{aligned} |a(\vec{y}, \vec{v})| &\leq \mu \left\{ \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} \left| \frac{\partial v_1}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} + \right. \\ &\sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} \left| \frac{\partial v_2}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} + \\ &+ \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} \left| \frac{\partial v_3}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} + \\ &+ \sum_{i=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\ &+ \sum_{i=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ &+ \sum_{i=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ &+ \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} \Big\}, \end{aligned}$$

Where $\mu = \max\{\mu_l, \bar{\mu}_l, \bar{\bar{\mu}}_l, \bar{\bar{\bar{\mu}}}_l\}, \forall l = 1, 2, 3, \forall i = 1, 2$.

$$\begin{aligned}
 |a(\vec{y}, \vec{v})| \leq & \mu \left(\left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} + \right. \\
 & \left. \sum_{j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_1}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} \right) \times \left(\left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \right. \\
 & \left. \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial v_1}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \right) + \\
 & \left(\left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} + \right. \\
 & \left. \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_2}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} \right) \times \\
 & \left(\left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \right. \\
 & \left. \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial v_2}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \right) + \\
 & + \left(\left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} + \right. \\
 & \left. \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_3}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} \right) \times \\
 & \times \left(\left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \right. \\
 & \left. \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial v_3}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \right) + \\
 & \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\
 & \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\
 & + \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\
 & + \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\
 & + \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\
 & \left. \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} \right) \quad (26)
 \end{aligned}$$

The RHS of (26), can be represented as:

$$\begin{aligned}
 |a(\vec{y}, \vec{v})| \leq & 4\mu \left\{ \int_{\Omega} |y_1|^2 dx + \sum_{j=1}^2 \int_{\Omega} \left| \frac{\partial y_1}{\partial x_j} \right|^2 dx \right\}^{\frac{1}{2}} \times \\
 & \times \left\{ \int_{\Omega} |v_1|^2 dx + \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial v_1}{\partial x_i} \right|^2 dx \right\}^{\frac{1}{2}} + \\
 & + 4\mu \left\{ \int_{\Omega} |y_2|^2 dx + \sum_{j=1}^2 \int_{\Omega} \left| \frac{\partial y_2}{\partial x_j} \right|^2 dx \right\}^{\frac{1}{2}} \times \\
 & \times \left\{ \int_{\Omega} |v_2|^2 dx + \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial v_2}{\partial x_i} \right|^2 dx \right\}^{\frac{1}{2}} + \\
 & + 4\mu \left\{ \int_{\Omega} |y_3|^2 dx + \sum_{j=1}^2 \int_{\Omega} \left| \frac{\partial y_3}{\partial x_j} \right|^2 dx \right\}^{\frac{1}{2}} \times \\
 & \times \left\{ \int_{\Omega} |v_3|^2 dx + \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial v_3}{\partial x_i} \right|^2 dx \right\}^{\frac{1}{2}} + \\
 & + \mu \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\
 & + \mu \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\
 & + \mu \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\
 & + \mu \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\
 & + \mu \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\
 & + \mu \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} \\
 \leq & 4\mu \left[\|y_1\|_{H_0^1(\Omega)} \|v_1\|_{H_0^1(\Omega)} + \right. \\
 & + \|y_2\|_{H_0^1(\Omega)} \|v_2\|_{H_0^1(\Omega)} + \\
 & + \|y_3\|_{H_0^1(\Omega)} \|v_3\|_{H_0^1(\Omega)} \left. \right] + \\
 & + \mu \left[\|y_2\|_{H_0^1(\Omega)} \|v_1\|_{H_0^1(\Omega)} + \right. \\
 & + \|y_1\|_{H_0^1(\Omega)} \|v_2\|_{H_0^1(\Omega)} + \\
 & + \|y_3\|_{H_0^1(\Omega)} \|v_1\|_{H_0^1(\Omega)} + \\
 & + \|y_1\|_{H_0^1(\Omega)} \|v_3\|_{H_0^1(\Omega)} + \\
 & + \|y_3\|_{H_0^1(\Omega)} \|v_2\|_{H_0^1(\Omega)} + \\
 & \left. + \|y_2\|_{H_0^1(\Omega)} \|v_3\|_{H_0^1(\Omega)} \right]. \quad (27)
 \end{aligned}$$

Then, by setting $\rho = 18\mu$, it concludes

$$|a(\vec{y}, \vec{v})| \leq \rho \|\vec{y}\|_{(H_0^1(\Omega))^3} \|\vec{v}\|_{(H_0^1(\Omega))^3}. \quad (28)$$

Besides this result, from assumptions 2.3.1 and then utilizing Proposition 2.1.6, once get the continuity of $\int_{\Omega} \bar{f}_l(x, y_l(x)) dx$ w.r.t. y_l (for $l = 1, 2, 3$).

Hence, (27) and (28), gives the continuity of $\vec{y} \mapsto \langle \bar{A}(\vec{y}), \vec{v} \rangle$ w.r.t. $\vec{y}$. In the RHS of (10), it is obvious that the linearity property of the functional $F(\vec{v})$ on $(H_0^1(\Omega))^3$ it satisfied, so it remains to show $F(\vec{v})$ it is bounded, so from theorem 2.1.2:

$$\begin{aligned}
 |F(\vec{v})| &\leq \sum_{l=1}^3 [\|h_l\|_{L^2(\Omega)} \|v_l\|_{L^2(\Omega)}] \leq \\
 \sum_{l=1}^3 [\gamma_l \|v_l\|_{L^2(\Omega)}] &\leq \gamma \|\vec{v}\|_{(L^2(\Omega))^3} \leq \\
 \gamma \|\vec{v}\|_{(H_0^1(\Omega))^3}
 \end{aligned} \quad (29)$$

where $\|h_l\|_{L^2(\Omega)} \leq \gamma_l$, $\gamma = \max(\gamma_l)$, $\forall l = 1, 2, 3$.

Since f_1 is strictly monotone, let $\vec{v} = \vec{y} - \vec{\bar{y}}$, then from (15), one has:

$$\langle \bar{A}(\vec{y}), \vec{y} - \vec{\bar{y}} \rangle = a(\vec{y}, \vec{y} - \vec{\bar{y}}) \quad (30)$$

$$\begin{aligned}
 &+ (f_1(x, y_1), y_1 - \bar{y}_1)_\Omega \\
 &+ (f_2(x, y_2), y_2 - \bar{y}_2)_\Omega \\
 &+ (f_3(x, y_3), y_3 - \bar{y}_3)_\Omega \\
 \langle \bar{A}(\vec{\bar{y}}), \vec{y} - \vec{\bar{y}} \rangle &= a(\vec{\bar{y}}, \vec{y} - \vec{\bar{y}}) \quad (31) \\
 &+ (f_1(x, \bar{y}_1), y_1 - \bar{y}_1)_\Omega \\
 &+ (f_2(x, \bar{y}_2), y_2 - \bar{y}_2)_\Omega \\
 &+ (f_3(x, \bar{y}_3), y_3 - \bar{y}_3)_\Omega
 \end{aligned}$$

$$\text{Subtracting (31) from (30) for } \vec{y} \neq \vec{\bar{y}}, \text{ to get} \\
 \langle \bar{A}(\vec{y}) - \bar{A}(\vec{\bar{y}}), \vec{y} - \vec{\bar{y}} \rangle > c \|\vec{y} - \vec{\bar{y}}\|_{(H_0^1(\Omega))^3}^2 > 0, \quad (32)$$

Thus, from the above steps, all the hypotheses of Theorem 2.1.3, are obtained, hence there exists a unique TRS $\vec{y} = (y_1, y_2, y_3) \in (H_0^1(\Omega))^3$ of (10).

Corollary 2.4.2. There exists a unique TRS $\vec{y} \in (H_0^1(\Omega))^3$ of the WF of the proposed TNLEPDEs ((1)-(3)), with the following homogeneous NBCs(HNBCs):

$$\frac{\partial y_1}{\partial n_1} = \sum_{i,j=1}^2 a_{1ij} \frac{\partial y_1}{\partial x_i} \cos(n_1, x_j) = 0, \quad \text{on } \Gamma \quad (33)$$

$$\frac{\partial y_2}{\partial n_2} = \sum_{i,j=1}^2 a_{2ij} \frac{\partial y_2}{\partial x_i} \cos(n_2, x_j) = 0, \quad \text{on } \Gamma \quad (34)$$

$$\frac{\partial y_3}{\partial n_3} = \sum_{i,j=1}^2 a_{3ij} \frac{\partial y_3}{\partial x_i} \cos(n_3, x_j) = 0, \quad \text{on } \Gamma \quad (35)$$

where n_ℓ , (for $\ell = 1, 2, 3$) is a normal unit vector on Γ and (n_ℓ, x_j) is the angle between n_ℓ and the x_j - axis.

Proof. The WF which results from ((1)-(3)) with the HNBCs ((33)-(35)) is similar to the WF in (10) with v_ℓ satisfies ((33)-(35)) for $\ell = 1, 2, 3$ resp., i.e.

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle = F(\vec{v}). \quad (36)$$

with $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ & $F(\vec{v})$ are defined in (11) & (12) resp.

Hence by Theorem 2.1.3, the WF (36) owns a unique TRS $\vec{y} \in (H_0^1(\Omega))^3$.

Corollary 2.4.3. There exists a unique TRS $\vec{y} \in (H^1(\Omega))^3$ of the WF of the proposed TNLEPDEs ((1)-(3)), with the HRBCs:

$$\begin{aligned}
 \alpha_1 y_1 + \frac{\partial y_1}{\partial n_1} &= \alpha_1 y_1 + \\
 + \sum_{i,j=1}^2 a_{1ij} \frac{\partial y_1}{\partial x_i} \cos(n_1, x_j) &= 0, \quad \text{on } \Gamma \quad (37)
 \end{aligned}$$

$$\begin{aligned}
 \alpha_2 y_2 + \frac{\partial y_2}{\partial n_2} &= \alpha_2 y_2 + \\
 + \sum_{i,j=1}^2 a_{2ij} \frac{\partial y_2}{\partial x_i} \cos(n_2, x_j) &= 0, \quad \text{on } \Gamma. \quad (38)
 \end{aligned}$$

$$\begin{aligned}
 \alpha_3 y_3 + \frac{\partial y_3}{\partial n_3} &= \alpha_3 y_3 + \\
 + \sum_{i,j=1}^2 a_{3ij} \frac{\partial y_3}{\partial x_i} \cos(n_3, x_j) &= 0, \quad \text{on } \Gamma \quad (39)
 \end{aligned}$$

where $g_1, g_2, g_3 \in L^2(\Gamma)$ and $\alpha_1, \alpha_2, \alpha_3 > 0$, and n_ℓ , ($\ell = 1, 2, 3$) is as defined in corollary 2.4.2.

Proof. The WF which results from ((1)-(3)) with the HRBCs ((37)-(39)) is similar to the WF in (10), with v_ℓ satisfies ((37)-(39)) for $\ell = 1, 2, 3$ resp., i.e.

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle = F(\vec{v}) \quad (40)$$

with $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ & $F(\vec{v})$ are defined in (11) & (12) resp. Hence by Theorem 2.1.3, the WF (40) owns a unique TRS $\vec{y} \in (H_0^1(\Omega))^3$.

Corollary 2.4.4. There exists a unique TRS $\vec{y} \in (H_0^1(\Omega))^3$ of the WF of the TNLEPDEs ((1)-(3)) with the following Mixed HBCs (MHBCs),

$$y_l = 0 \quad \text{on } \Gamma_D, l = 1, 2, 3 \quad (41)$$

$$\frac{\partial y_l}{\partial n_l} = 0 \quad \text{on } \Gamma_N, l = 1, 2, 3 \quad (42)$$

where the boundary Γ of Ω be divided in two open subset Γ_D and Γ_N , with $\Gamma = \Gamma_D \cup \Gamma_N$, $\Gamma_D \cap \Gamma_N = \emptyset$, and n_l is a normal unit vector on Γ_N .

Proof. The WF which results from ((1)-(3)) with the HNBCs ((41)-(42)) is similar to the WF in (10) with v_ℓ satisfies ((41)&(42)) for $\ell = 1, 2, 3$, i.e.

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle = F(\vec{v}). \quad (43)$$

with $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ & $F(\vec{v})$ are defined as in (11) & (12) resp.

Hence by Theorem 2.1.3, the WF (43) owns a unique TRS $\vec{y} \in (H_0^1(\Omega))^3$.

Example 2.4.5. Let $\Omega = [0, 1]^2$ with boundary $\Gamma = \partial\Omega$, and consider the TNLEPDEs in ((1)-(3)) with the HDBC in ((4)-(5)), where the coefficients in ((1)-(3)) are defined as

$$A_l y_l = - \sum_{i,j=1}^2 \frac{\partial}{\partial x_i} \left(e^{x_i^2 + l j x_j^2} \frac{\partial y_l}{\partial x_j} \right), c_l(x) = e^{l x_l},$$

$$B_l y_l = \sum_{i=1}^2 e^{l x_i} \frac{\partial y_l}{\partial x_i}, d_l(x) = l x_1^2 + l x_2^2 + 2l,$$

$$f_l(x, y_l) = |y_l| y_l, \quad \forall l = 1, 2, 3,$$

where $h_l(x)$ are given functions on Ω .

Now, since $f_l(x, y_l)$ in the given TNLEPDEs are satisfied Assumptions 2.3.1, then from theorem 2.1.3

the TNLEPDEs (1)-(3) with the HDBC (4)-(6), has a unique TRS $\vec{y} \in (H^1(\Omega))^3$.

2.5 Solvability of the Triple Nonlinear Nonhomogeneous Problems

In this section, the solvability of the WF of the TNLEPDEs with the NHBCs is studied.

Theorem 2.5.1. There exists a unique TRS $\vec{y} \in (H^1(\Omega))^3$ of the WF of the proposed TNLEPDEs ((1)-(3)), with the NHRBCs:

$$\alpha_1 y_1 + \frac{\partial y_1}{\partial n_1} = \alpha_1 y_1 + \quad (44)$$

$$+ \sum_{i,j=1}^2 \alpha_{1ij} \frac{\partial y_1}{\partial x_i} \cos(n_1, x_j) = g_1, \text{ on } \Gamma$$

$$\alpha_2 y_2 + \frac{\partial y_2}{\partial n_2} = \alpha_2 y_2 + \quad (45)$$

$$+ \sum_{i,j=1}^2 \alpha_{2ij} \frac{\partial y_2}{\partial x_i} \cos(n_2, x_j) = g_2, \text{ on } \Gamma$$

$$\alpha_3 y_3 + \frac{\partial y_3}{\partial n_3} = \alpha_3 y_3 + \quad (46)$$

$$+ \sum_{i,j=1}^2 \alpha_{3ij} \frac{\partial y_3}{\partial x_i} \cos(n_3, x_j) = g_3, \text{ on } \Gamma$$

where $g_1, g_2, g_3 \in L^2(\Gamma)$ and $\alpha_1, \alpha_2, \alpha_3 > 0$, and n_ℓ , ($\ell = 1, 2, 3$) is as defined in Corollary 2.4.2.

Proof. The WF of ((1)-(3)) and ((44)-(46)) results through multiplying these equations by the “test function” $(v_1, v_2, v_3) = \vec{v} \in \vec{V} = \{\vec{v}: \vec{v} \in (H^1(\Omega))^3, \vec{v} \text{ satisfies } ((44)-(46))\}$, then taking the integral and finally by utilizing the general Green’s theorem for the expressions that have 2nd order of partial derivatives, to get:

$$\alpha_1(y_1, v_1) + (\alpha_1 y_1, v_1)_\Gamma + b_1(y_1, v_1) + (c_1 y_1, v_1)_\Omega - (d_1 y_2, v_1)_\Omega + (d_2 y_3, v_1)_\Omega + \quad (47)$$

$$(f_1(x, y_1), v_1)_\Omega = (h_1, v_1)_\Omega + (g_1, v_1)_\Gamma.$$

$$\alpha_2(y_2, v_2) + (\alpha_2 y_2, v_2)_\Gamma + b_2(y_2, v_2) + (c_2 y_2, v_2)_\Omega + (d_1 y_1, v_2)_\Omega - (d_3 y_3, v_2)_\Omega + \quad (48)$$

$$(f_2(x, y_2), v_2)_\Omega = (h_2, v_2)_\Omega + (g_2, v_2)_\Gamma.$$

$$\alpha_3(y_3, v_3) + (\alpha_3 y_3, v_3)_\Gamma + b_3(y_3, v_3) + (c_3 y_3, v_3)_\Omega - (d_2 y_1, v_3)_\Omega + (d_3 y_2, v_3)_\Omega + \quad (49)$$

$$(f_3(x, y_3), v_3)_\Omega = (h_3, v_3)_\Omega + (g_3, v_3)_\Gamma.$$

Collecting (47)-(49), to get:

$$\langle \bar{A}(\vec{y}), \vec{v} \rangle = F(\vec{v}), \quad (50)$$

Where:

$$\langle \bar{A}(\vec{y}), \vec{v} \rangle = a(\vec{y}, \vec{v}) + (f_1(x, y_1), v_1)_\Omega + (f_2(x, y_2), v_2)_\Omega + (f_3(x, y_3), v_3)_\Omega, \quad (51)$$

with

$$\begin{aligned} a(\vec{y}, \vec{v}) = & \alpha_1(y_1, v_1) + (\alpha_1 y_1, v_1)_\Gamma + \\ & b_1(y_1, v_1) + (c_1 y_1, v_1)_\Omega - (d_1 y_2, v_1)_\Omega + \\ & (d_2 y_3, v_1)_\Omega \\ & + \alpha_2(y_2, v_2) + (\alpha_2 y_2, v_2)_\Gamma + \\ & b_2(y_2, v_2) + (c_2 y_2, v_2)_\Omega + (d_1 y_1, v_2)_\Omega - \\ & (d_3 y_3, v_2)_\Omega \\ & + \alpha_3(y_3, v_3) + (\alpha_3 y_3, v_3)_\Gamma + \\ & b_3(y_3, v_3) + (c_3 y_3, v_3)_\Omega \\ & - (d_2 y_1, v_3)_\Omega + (d_3 y_2, v_3)_\Omega \end{aligned} \quad (52)$$

here $a_i(y_l, v_l), b_i(y_l, v_l)$ are as defined in (12), $(\alpha_l y_l, v_l)_\Gamma = \int_\Gamma \alpha_l y_l v_l d\gamma, \forall l = 1, 2, 3 \ \& \ \forall v_l \in H^1(\Omega)$

$$F(\vec{v}) = \sum_{l=1}^3 [\int_\Omega h_l(x) v_l dx + \int_\Gamma g_l v_l d\gamma], \quad (53)$$

Now, to proof the coercivity and boundedness of $\langle \bar{A}(\vec{y}), \vec{v} \rangle$, since:

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle = & \int_\Omega \sum_{i,j=1}^2 \alpha_{1ij} \frac{\partial y_1}{\partial x_i} \frac{\partial y_1}{\partial x_j} dx + \\ & \int_\Gamma \alpha_1 y_1 y_1 d\gamma + \int_\Omega \sum_{i=1}^2 b_{1i}(x) \frac{\partial y_1}{\partial x_i} y_1 dx + \\ & \int_\Omega c_1(x) y_1 y_1 dx - \int_\Omega d_1(x) y_2 v_1 dx + \\ & \int_\Omega d_2(x) y_3 v_1 dx + \int_\Omega f_1(x, y_1) y_1 dx + \\ & \int_\Omega \sum_{i,j=1}^2 \alpha_{2ij} \frac{\partial y_2}{\partial x_i} \frac{\partial y_2}{\partial x_j} dx + \\ & \int_\Gamma \alpha_2 y_2 y_2 d\gamma + \int_\Omega \sum_{i=1}^2 b_{2i}(x) \frac{\partial y_2}{\partial x_i} y_2 dx + \\ & \int_\Omega c_2(x) y_2 y_2 dx + \int_\Omega d_1(x) y_1 v_2 dx - \\ & \int_\Omega d_3(x) y_3 v_2 dx + \int_\Omega f_2(x, y_2) y_2 dx + \\ & \int_\Omega \sum_{i,j=1}^2 \alpha_{3ij} \frac{\partial y_3}{\partial x_i} \frac{\partial y_3}{\partial x_j} dx + \int_\Gamma \alpha_3 y_3 y_3 d\gamma + \\ & \int_\Omega \sum_{i=1}^2 b_{3i}(x) \frac{\partial y_3}{\partial x_i} y_3 dx + \int_\Omega c_3(x) y_3 y_3 dx - \\ & \int_\Omega d_2(x) y_1 v_3 dx + \int_\Omega d_3(x) y_2 v_3 dx + \\ & \int_\Omega f_3(x, y_3) y_3 dx. \end{aligned}$$

Utilizing assumption 2.3.1, Letting $\frac{\partial y_l}{\partial x_i} y_l = \frac{1}{2} \frac{\partial}{\partial x_i} (y_l^2), l = 1, 2, 3$, for the 3rd, the 10th and the 17th terms, it becomes

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle \geq & \hat{c}_1 \sum_{i=1}^2 \int_\Omega \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx + \hat{c}_2 \int_\Gamma |y_1|^2 d\gamma + \\ & \sum_{i=1}^2 \int_\Omega b_{1i}(x) \frac{1}{2} \frac{\partial}{\partial x_i} (y_1^2) dx + \int_\Omega c_1(x) |y_1|^2 dx + \\ & \hat{c}_3 \sum_{i=1}^2 \int_\Omega \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx + \hat{c}_4 \int_\Gamma |y_2|^2 d\gamma + \\ & \sum_{i=1}^2 \int_\Omega b_{2i}(x) \frac{1}{2} \frac{\partial}{\partial x_i} (y_2^2) dx + \int_\Omega c_2(x) |y_2|^2 dx + \\ & \hat{c}_5 \sum_{i=1}^2 \int_\Omega \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx + \hat{c}_6 \int_\Gamma |y_3|^2 d\gamma + \\ & \sum_{i=1}^2 \int_\Omega b_{3i}(x) \frac{1}{2} \frac{\partial}{\partial x_i} (y_3^2) dx + \int_\Omega c_3(x) |y_3|^2 dx + \\ & \int_\Omega (f_1(x, y_1) - f_1(x, 0)) (y_1 - 0) dx + \\ & \int_\Omega (f_2(x, y_2) - f_2(x, 0)) (y_2 - 0) dx + \\ & \int_\Omega (f_3(x, y_3) - f_3(x, 0)) (y_3 - 0) dx \end{aligned} \quad (54)$$

Since f_l is monotone w.r.t. y_l , utilizing integrating by parts on the 3rd, 7th, and the 11th terms in (51), to get

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle \geq & \hat{c}_1 \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx + \sum_{i=1}^2 \int_{\Gamma} \frac{b_{1i}(x)}{2} |y_1|^2 d\gamma + \\ & \hat{c}_2 \int_{\Gamma} |y_1|^2 d\gamma + \int_{\Omega} \left(c_1(x) - \frac{1}{2} \sum_{i=1}^2 \frac{\partial b_{1i}}{\partial x_i} \right) |y_1|^2 dx + \\ & \hat{c}_3 \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx + \hat{c}_4 \int_{\Gamma} |y_2|^2 d\gamma + \\ & \sum_{i=1}^2 \int_{\Gamma} \frac{b_{2i}(x)}{2} |y_2|^2 d\gamma + \hat{c}_5 \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx + \\ & \int_{\Omega} \left(c_2(x) - \frac{1}{2} \sum_{i=1}^2 \frac{\partial b_{2i}}{\partial x_i} \right) |y_2|^2 dx + \\ & + \hat{c}_6 \int_{\Gamma} |y_3|^2 d\gamma + \sum_{i=1}^2 \int_{\Gamma} \frac{b_{3i}(x)}{2} |y_3|^2 d\gamma + \\ & \int_{\Omega} \left(c_3(x) - \frac{1}{2} \sum_{i=1}^2 \frac{\partial b_{3i}}{\partial x_i} \right) |y_3|^2 dx \end{aligned} \quad (55)$$

Utilizing (16) in (64), and with $b_{li} \geq 0$ for $l = 1, 2, 3, \forall i = 1, 2$, the (64) gives

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle \geq & \hat{c}_1 \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx + \\ & \hat{c}_3 \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx + \hat{c}_5 \sum_{i=1}^2 \int_{\Omega} \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx + \\ & \hat{c}_2 \int_{\Gamma} |y_1|^2 d\gamma + \hat{c}_4 \int_{\Gamma} |y_2|^2 d\gamma + \hat{c}_6 \int_{\Gamma} |y_3|^2 d\gamma, \\ & = C_0 (\sum_{l=1}^3 \int_{\Omega} |\nabla y_l|^2 dx + \sum_{l=1}^3 \int_{\Gamma} |y_l|^2 d\gamma), \end{aligned} \quad (56)$$

with $\tau = \min(\hat{c}_2, \hat{c}_4, \hat{c}_6)$, $C_0 = \min(\hat{c}_1, \hat{c}_3, \hat{c}_5, \tau)$

Now, from the assumption on Ω , and consider $\Gamma_1 \subset \Gamma$ is a measurable subset, $|\Gamma_1| > 0$, then there exist constants $\sigma_1(\Gamma_1), \sigma_2(\Gamma_1), \sigma_3(\Gamma_1) > 0$ independent of $\vec{y} \in (H^1(\Omega))^3$ (from corollary 2.4.2), s.t.

$$\begin{aligned} \langle \bar{A}(\vec{y}), \vec{y} \rangle \geq & C_0 (\sum_{l=1}^3 \int_{\Omega} |\nabla y_l|^2 dx + \sum_{l=1}^3 \int_{\Gamma_1} |y_l|^2 d\gamma) \\ & = \sigma_4 (\sum_{l=1}^3 \int_{\Omega} |\nabla y_l|^2 dx + \sum_{l=1}^3 \int_{\Gamma_1} |y_l|^2 d\gamma), \\ & \geq \sigma_4 \|\vec{y}\|_{(H^1(\Omega))^3}^2, \sigma_4 = C_0 \min(\sigma_1, \sigma_2, \sigma_3) \end{aligned} \quad (54)$$

In addition, since $a_{lij}(x), b_{li}(x), c_l(x), d_l(x) \in L^\infty(\Omega)$, ($\forall l = 1, 2, 3, \forall i, j = 1, 2$), and $\forall \lambda_l = \max_{l=1,2} |\alpha_l|$

$$\left| \int_{\Gamma} \sum_{l=1}^3 \alpha_l y_l v_l d\gamma \right| \leq \sum_{l=1}^3 \lambda_l \left| \int_{\Gamma} y_l v_l d\gamma \right|, \quad (57)$$

Utilizing (55), beside the ((20)-(25)), to get

$$\begin{aligned} |\langle \bar{A}(\vec{y}), \vec{y} \rangle| \leq & \sum_{i,j=1}^2 \mu_1 \left| \int_{\Omega} \frac{\partial y_1}{\partial x_i} \frac{\partial v_1}{\partial x_j} dx \right| + \\ & \sum_{i,j=1}^2 \mu_2 \left| \int_{\Omega} \frac{\partial y_2}{\partial x_i} \frac{\partial v_2}{\partial x_j} dx \right| + \sum_{i,j=1}^2 \mu_3 \left| \int_{\Omega} \frac{\partial y_3}{\partial x_i} \frac{\partial v_3}{\partial x_j} dx \right| \\ & + \sum_{l=1}^3 \lambda_l \left| \int_{\Gamma} y_l v_l d\gamma \right| + \sum_{i=1}^2 \bar{\mu}_1 \left| \int_{\Omega} \frac{\partial y_1}{\partial x_i} v_1 dx \right| + \\ & \sum_{i=1}^2 \bar{\mu}_2 \left| \int_{\Omega} \frac{\partial y_2}{\partial x_i} v_2 dx \right| + \sum_{i=1}^2 \bar{\mu}_3 \left| \int_{\Omega} \frac{\partial y_3}{\partial x_i} v_3 dx \right| + \\ & \sum_{l=1}^3 \bar{\mu}_l \left| \int_{\Omega} y_l v_l dx \right| + \bar{\bar{\mu}}_1 \left| \int_{\Omega} y_2 v_1 dx \right| + \\ & \bar{\bar{\mu}}_1 \left| \int_{\Omega} y_1 v_2 dx \right| + \bar{\bar{\mu}}_2 \left| \int_{\Omega} y_3 v_1 dx \right| + \bar{\bar{\mu}}_2 \left| \int_{\Omega} y_1 v_3 dx \right| + \\ & \bar{\bar{\mu}}_3 \left| \int_{\Omega} y_3 v_2 dx \right| + \bar{\bar{\mu}}_3 \left| \int_{\Omega} y_2 v_3 dx \right|. \end{aligned}$$

And by utilizing Theorem 2.1.3, to get

$$\begin{aligned} |\langle \bar{A}(\vec{y}), \vec{v} \rangle| \leq & \mu \left\{ \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} \left| \frac{\partial v_1}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} + \right. \\ & \left(\int_{\Gamma} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Gamma} |v_1|^2 dx \right)^{\frac{1}{2}} + \\ & \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} \left| \frac{\partial v_2}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} + \\ & \left(\int_{\Gamma} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Gamma} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ & \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} \left| \frac{\partial v_3}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} + \\ & \left(\int_{\Gamma} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Gamma} |v_3|^2 dx \right)^{\frac{1}{2}} + \\ & \sum_{i=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_1}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\ & \sum_{i=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_2}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ & \sum_{i=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_3}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\ & \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\ & \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ & \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\ & \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ & \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\ & \left. \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} \right\} \end{aligned} \quad (58)$$

where $\mu = \max\{\mu_l, \lambda_l, \bar{\mu}_l, \bar{\bar{\mu}}_l, \bar{\bar{\mu}}_l\}, \forall l = 1, 2, 3$.

Now, theorem 2.1.7 is used on the 2th, 4th and 6th terms in the previous inequality, then the resulting inequality can be written as:

$$\begin{aligned} |\langle \bar{A}(\vec{y}), \vec{v} \rangle| \leq & \mu \left(\left\{ \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} + \sum_{j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_1}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} \right\} \times \right. \\ & \left. \left\{ \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial v_1}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \right\} \right. \\ & \left. + \left\{ \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} + \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_2}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} \right\} \times \right. \\ & \left. \left\{ \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial v_2}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \right\} \right. \\ & \left. + \left\{ \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} + \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_3}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} \right\} \times \right. \\ & \left. \left\{ \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial v_3}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \right\} \right) \end{aligned}$$

$$\begin{aligned}
 & \left\{ \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial v_2}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \right\} \\
 & + \left\{ \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} + \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial y_3}{\partial x_j} \right|^2 dx \right)^{\frac{1}{2}} \right\} \times \\
 & \left\{ \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \sum_{i,j=1}^2 \left(\int_{\Omega} \left| \frac{\partial v_3}{\partial x_i} \right|^2 dx \right)^{\frac{1}{2}} \right\} \\
 & + \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\
 & \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\
 & \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\
 & + \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\
 & \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\
 & \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} + \\
 & \bar{c}_1 \left(\int_{\Omega} |y_1|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_1|^2 dx \right)^{\frac{1}{2}} + \\
 & \bar{c}_2 \left(\int_{\Omega} |y_2|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_2|^2 dx \right)^{\frac{1}{2}} + \\
 & \bar{c}_3 \left(\int_{\Omega} |y_3|^2 dx \right)^{\frac{1}{2}} \left(\int_{\Omega} |v_3|^2 dx \right)^{\frac{1}{2}} \quad (59) \\
 & |\langle \bar{A}(\vec{y}), \vec{v} \rangle| \leq \\
 & \mu_3 [\|y_1\|_{H^1(\Omega)} \|v_1\|_{H^1(\Omega)} + \|y_2\|_{H^1(\Omega)} \|v_2\|_{H^1(\Omega)} + \\
 & \|y_3\|_{H^1(\Omega)} \|v_3\|_{H^1(\Omega)} + \|y_2\|_{H^1(\Omega)} \|v_1\|_{H^1(\Omega)} + \\
 & \|y_1\|_{H^1(\Omega)} \|v_2\|_{H^1(\Omega)} + \|y_3\|_{H^1(\Omega)} \|v_1\|_{H^1(\Omega)} + \\
 & \|y_1\|_{H^1(\Omega)} \|v_3\|_{H^1(\Omega)} + \|y_3\|_{H^1(\Omega)} \|v_2\|_{H^1(\Omega)} + \\
 & \|y_2\|_{H^1(\Omega)} \|v_3\|_{H^1(\Omega)} + \bar{c}_1 \|y_1\|_{H^1(\Omega)} \|v_1\|_{H^1(\Omega)} + \\
 & \bar{c}_2 \|y_2\|_{H^1(\Omega)} \|v_2\|_{H^1(\Omega)} + \bar{c}_3 \|y_3\|_{H^1(\Omega)} \|v_3\|_{H^1(\Omega)}], \\
 & \leq \rho \|\vec{y}\|_{(H^1(\Omega))^3} \|\vec{v}\|_{(H^1(\Omega))^3}, \quad (60)
 \end{aligned}$$

With $\rho = 12\mu_3$, $\mu_3 = \mu \max_{1 \leq l \leq 3} (1 + \bar{c}_l)$.

From (58) and (28), the continuity of $\vec{y} \mapsto \langle \bar{A}(\vec{y}), \vec{v} \rangle$ w.r.t. $\vec{y}$, is obtained.

The continuity of the RHS $F(\vec{v})$ in (50) is proved as:

$$\begin{aligned}
 |F(\vec{v})| & \leq \sum_{l=1}^3 \|h_l(x)\|_{L^2(\Omega)} \|v_l\|_{L^2(\Omega)} \\
 & + \sum_{l=1}^3 \|g_l(x)\|_{L^2(\Gamma)} \|v_l\|_{L^2(\Gamma)} \\
 & \leq \sum_{l=1}^3 [\gamma_l \|v_l\|_{H^1(\Omega)} + \bar{\gamma}_l \bar{\gamma}_l \|v_l\|_{H^1(\Omega)}], \\
 & \leq \check{C} \|\vec{v}\|_{(H^1(\Omega))^2}^2
 \end{aligned}$$

where $\|h_l\|_{L^2(\Omega)} \leq \gamma_l$, $\|g_l(x)\|_{L^2(\Gamma)} \leq \bar{\gamma}_l$,

$\gamma = \max(\gamma_l, \bar{\gamma}_l \bar{\gamma}_l)$, $\forall l = 1, 2, 3$, and $\check{C} = 3\gamma$, therefore $F(\vec{v})$ is linear and bounded, hence by theorem 2.1.3, the uniqueness of a TRS $\vec{y} \in (H^1(\Omega))^3$ of the WF (50) is obtained.

Corollary 2.5.2. There exists a unique TRS $\vec{y} \in (H^1(\Omega))^3$, for the WF of the TEPDEs ((1)-(3)), with the nonhomogeneous DBCs (NHDBC)s:

$$y_1 = g_1, \text{ on } \Gamma \quad (61)$$

$$y_2 = g_2, \text{ on } \Gamma \quad (62)$$

$$y_3 = g_3, \text{ on } \Gamma \quad (63)$$

where $g_1(x), g_2(x), g_3(x) \in L^2(\Gamma)$, $\vec{g} = (g_1, g_2, g_3)$.

Proof. Assume, $\vec{w} = (w_1, w_2, w_3) \in (H^2(\Omega))^3$, for which $\vec{w} = \vec{g} = (g_1, g_2, g_3)$ on Γ . Set $\vec{y} = \vec{w} + \vec{z}$ with $\vec{z} = (z_1, z_2, z_3) \in (H_0^2(\Omega))^3$ and the functions f_l , (for $l = 1, 2, 3$) is satisfies Assumptions 2.3.1 with one different that $\vec{z}$ instead of $\vec{y}$. Then the WF obtained from ((1)-(3)) with the NHDBC's ((61)-(63)) is similar to the WF in (50), i.e

$$\langle \bar{A}(z), \vec{v} \rangle = H(\vec{v}) \quad (64)$$

here

$$\begin{aligned}
 \langle \bar{A}(z), \vec{v} \rangle & = a(\vec{z}, \vec{v}) + (f_1(x, z_1 + w_1), v_1)_{\Omega} + \\
 & (f_2(x, z_2 + w_2), v_2)_{\Omega} + (f_3(x, z_3 + w_3), v_3)_{\Omega}, \text{ and} \\
 & H(\vec{v}) = F(\vec{v}) + a(\vec{w}, \vec{v})
 \end{aligned}$$

with $a(\vec{z}, \vec{v})$ ($a(\vec{w}, \vec{v})$) is as defined in (12) with one different that $\vec{z}$ ($\vec{w}$) instead of $\vec{y}$, and $F(\vec{v})$ is as defined in (13).

In this point, for fixed $\vec{w}$, the coercivity and the continuity of the $\langle \bar{A}(z), \vec{v} \rangle$ is obtained by the same ways that were used in the proof of theorem 2.4.1, and the continuity of the RHS of (64) is obtained depending on the continuity of the $F(\vec{v})$ and $a(\vec{w}, \vec{v})$, i.e.

$$\begin{aligned}
 |a(\vec{w}, \vec{v})| & \leq \rho \|\vec{w}\|_{(H_0^1(\Omega))^3} \|\vec{v}\|_{(H_0^1(\Omega))^3} \\
 & \leq \rho \bar{\rho} \|\vec{v}\|_{(H_0^1(\Omega))^3}^2 \quad (65)
 \end{aligned}$$

$$|F(\vec{v})| \leq \gamma \|\vec{v}\|_{(L^2(\Omega))^3} \leq \gamma \|\vec{v}\|_{(H_0^1(\Omega))^3}^2 \quad (66)$$

From (63a) and (63b), we get that

$$|H(\vec{v})| \leq \bar{\gamma} \|\vec{v}\|_{(H_0^1(\Omega))^3}^2, \text{ where } \bar{\gamma} = \rho \bar{\rho} + \gamma.$$

Therefore, by Theorem 2.1.3, $\vec{z} \in (H_0^1(\Omega))^3$, or $\vec{y} \in (H^1(\Omega))^3$ is a unique TRS of the WF (64).

Corollary 2.5.3. There is a unique TRS $\vec{y} = (y_1, y_2, y_3) \in (H^1(\Omega))^3$ of the WF of the proposed TNLEPDEs ((1)-(3)), with the following nonhomogeneous NBCs (NHNBCs):

$$\frac{\partial y_1}{\partial n_1} = \sum_{i,j=1}^2 a_{1ij} \frac{\partial y_1}{\partial x_i} \cos(n_1, x_j) = g_1(x), \text{ on } \Gamma \quad (67)$$

$$\frac{\partial y_2}{\partial n_2} = \sum_{i,j=1}^2 a_{2ij} \frac{\partial y_2}{\partial x_i} \cos(n_2, x_j) = g_2(x), \text{ on } \Gamma \quad (68)$$

$$\frac{\partial y_3}{\partial n_3} = \sum_{i,j=1}^2 a_{3ij} \frac{\partial y_3}{\partial x_i} \cos(n_3, x_j) = g_3(x), \text{ on } \Gamma \quad (69)$$

where $(g_1, g_2, g_3) \in (L^2(\Gamma))^3$ and n_ℓ , (for $\ell = 1, 2, 3$) is an outer normal vector on Γ and (n_ℓ, x_j) is the angle between the x_j - axis and n_ℓ .

Proof. The WF results from ((1)-(3)) with the NHNBCs ((61)-(63)) is similar to the WF in (50), i.e

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle = F(\vec{v}). \quad (70)$$

with $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ is as defined in (50) but with neglecting all the terms that have the forms $(\alpha_l y_l, v_l)_\Gamma$, for $l = 1, 2, 3$, and $\forall v_l \in H^1(\Omega)$.

$$F(\vec{v}) = \sum_{l=1}^3 [\int_\Omega h_l v_l dx + \int_\Gamma g_l v_l d\gamma],$$

In this case, the proof of the existence of a unique TRS $\vec{y} \in (H^1(\Omega))^3$ of the WF (70) is obtained directly from the above corollary 2.5.2.

Corollary 2.5.4. There exists a unique TRS $\vec{y} \in (H_0^2(\Omega))^3$ of the WF for the TNLEPDEs ((1)-(3)), with the homogenous Robin BCs (HRBCs)

$$\alpha_1 y_1 + \frac{\partial y_1}{\partial n_1} = \alpha_1 y_1 + \sum_{i,j=1}^2 a_{1ij} \frac{\partial y_1}{\partial x_i} \cos(n_1, x_j) = 0, \text{ on } \Gamma, \quad (71)$$

$$\alpha_2 y_2 + \frac{\partial y_2}{\partial n_2} = \alpha_2 y_2 + \sum_{i,j=1}^2 a_{2ij} \frac{\partial y_2}{\partial x_i} \cos(n_2, x_j) = 0, \text{ on } \Gamma, \quad (72)$$

$$\alpha_3 y_3 + \frac{\partial y_3}{\partial n_3} = \alpha_3 y_3 + \sum_{i,j=1}^2 a_{3ij} \frac{\partial y_3}{\partial x_i} \cos(n_3, x_j) = 0, \text{ on } \Gamma, \quad (73)$$

where $\alpha_1, \alpha_2, \alpha_3$ and n_ℓ , (for $\ell = 1, 2, 3$) are as defined in theorem 2.5.1.

Proof. The WF results from ((1)-(3)) with the NHNBCs ((61)-(63)) is similar to the WF in (50), i.e

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle = F(\vec{v}), \quad (74)$$

where $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ is exactly as defined in (11), then from the proof of theorem 2.5.1, the coercivity and the boundedness for $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ is obtained directly. On the other hand, the function $F(\vec{v})$ in the RHS of (74) will be in the form:

$$F(\vec{v}) = \sum_{l=1}^3 [\int_\Omega h_l v_l dx], \quad \forall v_l \in H^1(\Omega),$$

The demonstration of that $F(\vec{v})$ is bounded is obtained directly, since it is an especial case from those was proved in theorem 2.5.1, hence by Theorem 2.1.3, $\vec{y} \in (H^1(\Omega))^3$ is a unique TRS of (64).

Example 2.5.5. Let $\Omega = [0, 1]^2$ with boundary $\Gamma = \partial\Omega$, and consider the TNLEPDEs in ((1)-(3)) with the following NHRBCs (44)-(46), where the coefficients in ((1)-(3)) are assumed to be:

$$A_l y_l = - \sum_{i,j=1}^2 \frac{\partial}{\partial x_i} \left(e^{x_i^2 + l j x_j^2} \frac{\partial y_l}{\partial x_j} \right), c_l(x) = e^{l x_l},$$

$$B_l y_l = \sum_{i=1}^2 e^{l x_i} \frac{\partial y_l}{\partial x_i}, d_l(x) = l x_1^2 + l x_2^2 + 2l, \\ f_l(x, y_l) = |y_l| y_l, \alpha_l = l \quad \forall l = 1, 2, 3,$$

where $h_l(x)$ are given functions on Ω and $g_l(x)$ are given functions on Γ

Now, since $f_l(x, y_l)$ in the given TNLEPDEs are satisfied Assumptions 2.3.1, then from theorem 2.5.1 the TNLEPDEs (1)-(3) with the NHRBCs (44)-(46), has a unique TRS $\vec{y} \in (H_0^1(\Omega))^3$.

2.6 Solvability of the Triple Nonlinear with Mixed Boundary Conditions

The solvability for the WF of the TNLEPDEs with Mixed BCs (MBCs), is studied as follows.

Theorem 2.6.1. There exists a unique TRS $\vec{y} \in (H^2(\Omega))^3$ of the WF of the TNLEPDEs ((1)-(3)) with the following mixed BCs (MBCs),

$$y_l = g_{lD} \quad \text{on} \quad \Gamma_D, l = 1, 2, 3, \quad (75)$$

$$\frac{\partial y_l}{\partial n_l} = g_{lN} \quad \text{on} \quad \Gamma_N, l = 1, 2, 3, \quad (76)$$

where the boundary Γ of Ω be divided in two open subset Γ_D and Γ_N , with $\Gamma = \Gamma_D \cup \Gamma_N$, $\Gamma_D \cap \Gamma_N = \emptyset$, $g_{lD} \in L^2(\Gamma_D)$, $g_{lN} \in L^2(\Gamma_N)$ and n_l is a normal unit vector on Γ_N .

Proof. The WF results from ((1)-(3)) with the NHNBCs ((75)-(76)) is similar to the WF in (50), i.e

$$\langle \bar{A}(\vec{y}), \vec{y} \rangle = F(\vec{v}), \quad (77)$$

with $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ is as defined in (11) (or as defined in (50) but with neglecting all the terms that have the forms $(\alpha_l y_l, v_l)_\Gamma$, for $l = 1, 2, 3$), and

$$F(\vec{v}) = \sum_{l=1}^3 [\int_\Omega h_l(x) v_l dx + \int_{\Gamma_D} g_{lD} v_l d\gamma_D + \int_{\Gamma_N} g_{lN} v_l d\gamma_N], \quad \forall v_l \in H^1(\Omega)$$

The proof of the coercivity and the boundedness for $\langle \bar{A}(\vec{y}), \vec{y} \rangle$ is the same so were proved in Theorem 2.4.1, and hence to prove the solvability of the WF (66) through applying theorem 2.1.1, it remains to demonstrate that $F(\vec{v})$ in its RHS is bounded, so by utilizing Theorem 2.1.3 and Theorem 2.1.7, one has

$$|F(\vec{v})| \leq \sum_{l=1}^3 [|(h_l, v_l)_\Omega| + |(g_{lD}, v_l)_{\Gamma_D}| + |(g_{lN}, v_l)_{\Gamma_N}|] \\ \leq \sum_{l=1}^3 [\|h_l\|_{L^2(\Omega)} \|v_l\|_{L^2(\Omega)} + \|g_{lD}(x)\|_{L^2(\Gamma_D)} \|v_l\|_{L^2(\Gamma_D)} + \|g_{lN}\|_{L^2(\Gamma_N)} \|v_l\|_{L^2(\Gamma_N)}], \\ \leq \sum_{l=1}^3 [\gamma_l \|v_l\|_{H^1(\Omega)} + \bar{\gamma}_l \|v_l\|_{L^2(\Gamma_D)} + \bar{\gamma}_l \|v_l\|_{L^2(\Gamma_N)}] \\ \text{where} \quad \|h_l\|_{L^2(\Omega)} \leq \gamma_l, \quad \|g_{lD}\|_{L^2(\Gamma_D)} \leq \bar{\gamma}_l, \\ \|g_{lN}\|_{L^2(\Gamma_N)} \leq \bar{\gamma}_l, \text{ for } l = 1, 2, 3.$$

By utilizing theorem 2.1.5,

$$\begin{aligned} \|v_l\|_{L^2(\Gamma_D)} &\leq c_l \|v_l\|_{H^1(\Omega)}, \text{ for } l = 1, 2, 3, \\ \|v_l\|_{L^2(\Gamma_N)} &\leq \bar{c}_l \|v_l\|_{H^1(\Omega)}, \text{ for } l = 1, 2, 3. \end{aligned}$$

Thus, with $\check{C} = 3\max(\gamma_l, c_l \bar{\gamma}_l, \bar{c}_l \bar{\gamma}_l)$

$$|F(\vec{v})| \leq \check{C} \|\vec{v}\|_{(H^1(\Omega))^3}.$$

Hence, the uniqueness of a TRS $\vec{y} \in (H^1(\Omega))^3$ of the WF (64) is obtained.

Corollary 2.6.2. There exists a unique TRS $\vec{y} \in (H^2(\Omega))^3$ of the WF of the TNLEPDEs ((1)-(3)) with the following Mixed BCs (MBCs),

$$y_l = 0, \text{ on } \Gamma_D, l = 1, 2, 3, \quad (75)$$

$$\frac{\partial y_l}{\partial n_l} = g_{lN}, \text{ on } \Gamma_N, l = 1, 2, 3, \quad (76)$$

where $g_{lN} \in L^2(\Gamma_N)$.

Proof. The WF results from ((1)-(3)) with the BCs ((75)-(76)) is similar to those which is obtained in theorem 2.6.1, with one different that the $F(\vec{v})$ will be in the form $\forall v_l \in H^1(\Omega)$

$$F(\vec{v}) = \sum_{l=1}^3 [\int_{\Omega} h_l(x) v_l dx + \int_{\Gamma_N} g_{lN} v_l d\gamma_N].$$

Which is an especial case from those was obtained in Theorem 2.6.1. Hence the uniqueness of a TRS $\vec{y} \in (H^1(\Omega))^3$ is obtained.

Corollary 2.6.3. There is a unique TRS $\vec{y} \in (H^2(\Omega))^3$ of the WF of the TNLEPDEs ((1)-(3)) with the following Mixed BCs (MBCs),

$$y_l = g_{lD}, \text{ on } \Gamma_D, l = 1, 2, 3, \quad (77)$$

$$\frac{\partial y_l}{\partial n_l} = 0, \text{ on } \Gamma_N, l = 1, 2, 3, \quad (78)$$

where $g_{lD} \in L^2(\Gamma_D)$.

Proof. Again, the WF results from ((1)-(3)) with the BCs ((75)-(76)) is similar to those which is obtained in theorem 2.6.1, with one different that the $F(\vec{v})$ will be in the form $\forall v_l \in H^1(\Omega)$:

$$F(\vec{v}) = \sum_{l=1}^3 [\int_{\Omega} h_l(x) v_l dx + \int_{\Gamma_D} g_{lD} v_l d\gamma_D],$$

Which is an especial case from those was obtained in Theorem 2.6.1. Hence the uniqueness of a TRS $\vec{y} \in (H^1(\Omega))^3$ is obtained.

3 CONCLUSIONS

The MBTH with the help of the PFI were utilized successfully to prove the existence of a unique TRS (in infinite dimension) of the WF for the TNLEPDEs associated with each kind of the homogenous BCs (DBC, NBC, RBC and MBCs). While the MBTH

with the help of both, the general PFI and the TRP were utilized successfully to prove the existence of a unique TRS of the WF associated with each kind of the nonhomogeneous BCs (DBC, NBC, RBC and MBCs). The results of this paper play an important role to help many investigators who they interest about solving these types of problems numerically.

REFERENCES

- [1] R. G. MacDonald, A. Yakovlev, and V. Pacheco-Peña, "Solving partial differential equations with waveguide-based metatronic networks," *Advanced Photonics Nexus*, vol. 3, no. 5, art. 056007, Oct. 2024.
- [2] J. Tu, G. H. Yeoh, C. Liu, and Y. Tao, *Computational Fluid Dynamics: A Practical Approach*, 4th ed. Oxford, U.K.: Elsevier, 2023, p. 560.
- [3] Y. Swapna, V. K. Nirmale, N. Pavani, C. Singh, R. Ranganathan, A. R. Thontla, and N. M. Kumar, "Applications of Partial Differential Equations in Fluid Physics," *Communications on Applied Nonlinear Analysis*, vol. 31, no. 1, pp. 396-409, Mar. 2024.
- [4] J. Tu, G. H. Yeoh, C. Liu, and Y. Tao, *Computational Fluid Dynamics: A Practical Approach*, 4th ed. Oxford, U.K.: Elsevier, 2023, p. 560.
- [5] Y. Li, J. Mao, X. Tian, H. Song, and J. Ren, "Identification of Salvianolic Acid A as a potent inhibitor of PDEs to enhance proliferation of human neural stem cells," *Journal of Molecular Structure*, vol. 1324, art. 140905, Dec. 2025.
- [6] K. Charles, "Introduction to Partial Differential Equations and Machine Learning Solutions," *Research and Invention Journal of Engineering and Physical Sciences*, vol. 3, no. 1, pp. 52-61, May 2024.
- [7] L. C. Evans, *Partial Differential Equations*. Providence, RI, USA: American Mathematical Society, 2022, p. 749.
- [8] W. Xin, W. Zhong, Y. Shi, Y. Shi, J. Jing, T. Xu, et al., "Low-Dimensional-Materials-Based Photodetectors for Next-Generation Polarized Detection and Imaging," *Advanced Materials*, vol. 36, no. 7, art. 2306772, 2024.
- [9] E. A. Alnussairy and A. Bakheet, "MHD micropolar blood flow model through a multiple stenosed artery," in *AIP Conference Proceedings*, vol. 2183, pp. 09001-09008, 2019.
- [10] J. A. Al-Hawasy and N. A. Al-Ajeeli, "The continuous classical boundary optimal control of triple nonlinear elliptic partial differential equations with state constraints," *Iraqi Journal of Science*, vol. 62, no. 9, pp. 3020-3030, Sep. 2021.
- [11] Y. Gu and J. Shen, "Accurate and Efficient Spectral Methods for Elliptic PDEs in Complex Domains," *Journal of Scientific Computing*, vol. 83, no. 42, pp. 1-20, May 2020.
- [12] D. P. Covei, "On a Parabolic Partial Differential Equation and System Modeling a Production Planning Problem," *Electronic Research Archive*, vol. 30, no. 4, pp. 1340-1353, Mar. 18, 2022.

- [13] C. Wang and A. Townsend, "Operator Learning for Hyperbolic Partial Differential Equations," *Journal of Machine Learning Research*, vol. 26, pp. 1-44, Sep. 2025.
- [14] V. Mikhailets and O. Atlasiuk, "The solvability of inhomogeneous boundary-value problems in Sobolev spaces," *Banach Journal of Mathematical Analysis*, vol. 18, no. 2, art. 12, Feb. 2024.
- [15] B. T. Bilalov and S. R. Sadigova, "On solvability in the small of higher order elliptic equations in grand-Sobolev spaces," *Complex Variables and Elliptic Equations*, vol. 66, pp. 2117-2130, Aug. 2020.
- [16] Y. Zeren, M. Ismailov, and F. Sirin, "On basicity of the system of eigenfunctions of one discontinuous spectral problem for second order differential equation for grand-Lebesgue space," *Turkish Journal of Mathematics*, vol. 44, no. 5, pp. 1595-1612, Sep. 2020.
- [17] J. A. Al-Hawasy and L. H. Ali, "Constraints Optimal Control Governing by Triple Nonlinear Hyperbolic Boundary Value Problem," *Journal of Applied Mathematics*, vol. 2020, no. 1, pp. 1-14, Apr. 2020.
- [18] W. Cao and W. Zhang, "Machine Learning of Partial Differential Equations from Noise Data," *Theoretical and Applied Mathematics Letters*, vol. 13, no. 6, pp. 1-6, Nov. 2023.
- [19] M. Subasi, "An Optimal Control Problem Governed by the Potential of a Linear Schrödinger Equation," *Applied Mathematics and Computation*, vol. 131, no. 1, pp. 95-106, Sep. 2002.
- [20] E. Le Donne, *General Theory of Carnot-Carathéodory Spaces*, vol. 36. Cham, Switzerland: Springer, [Online]. Available: https://doi.org/10.1007/978-3-031-98832-5_4.
- [21] M. Andrea, A. Quarteroni, and S. Salsa, *Optimal Control of Partial Differential Equations: Analysis, Approximation and Applications*. Cham, Switzerland: Springer, 2021, p. 498.
- [22] S. J. Al-Qaisi, G. M. Kadhem, and J. Al-Hawasy, "Mixed Optimal Control Vector for a Boundary Value Problem of Couple Nonlinear Elliptic Equations," *Iraqi Journal of Science*, vol. 63, no. 9, pp. 3861-3866, Sep. 2022.
- [23] W. Zheng and H. Qi, "On Friedrichs-Poincaré-Type Inequalities," *Journal of Mathematical Analysis and Applications*, vol. 304, no. 2, pp. 542-551, Feb. 2005.
- [24] F. B. Yagüe and M. J. Carro, "Boundary value problems in graph Lipschitz domains in the plane with A_∞ -measures on the boundary," *Advances in Mathematics*, vol. 486, art. 110734, Jun. 2025.
- [25] F. Tröltzsch, *Optimal Control of Partial Differential Equations: Theory, Methods and Applications*. Providence, RI, USA: American Mathematical Society, 2010, p. 395.
- [26] I. Chrysoverghi and A. Bacopoulos, "Approximation of Relaxed Nonlinear Parabolic Optimal Control Problems," *Journal of Optimization Theory and Applications*, vol. 77, no. 1, pp. 31-50, Apr. 1993.
- [27] A. Manzoni, A. Quarteroni, and S. Salsa, *Optimal Control of Partial Differential Equations: Analysis, Approximation and Applications*. Cham, Switzerland: Springer, 2021, p. 498.
- [28] T. Alazard, "Analysis and Partial Differential Equations," in *Universitext*. Cham, Switzerland: Springer, 2024, pp. 165-197, [Online]. Available: https://doi.org/10.1007/978-3-031-70909-8_7.
- [29] G.-Q. G. Chen, G. E. Comi, and M. Torres, "Cauchy Fluxes and Gauss-Green Formulas for Divergence-Measure Fields Over General Open Sets," *Archive for Rational Mechanics and Analysis*, vol. 233, pp. 87-166, Jun. 2019.
- [30] V. E. S. Szabó, "Completely monotone functions in general and some applications," *Journal of Mathematical Analysis and Applications*, vol. 554, no. 2, art. 129984, Aug. 2026.